
CAREER OBJECTIVE

To work in an organization where I can acquire new knowledge, sharpen my skills and put my efforts for achieving organizational as well as individual goals.

EDUCATION

Examination	University/Board	Year	CGPA/Percentage
B.E.(EXTC) (Pursuing)	St. Francis Institute of Technology, University of Mumbai	2018	8.03
H.S.C.	Maharashtra State Board	2014	81.08%
S.S.C.	Maharashtra State Board	2012	89.64%

INTERESTS

My interests are in Affective Computing (mainly on Speech emotion Recognition) and Speech processing, and broadly, to solve multimodal AI problems using machine learning techniques.

ACADEMIC PROJECTS

Harmony Search for Feature Selection in ASER

July 2017 - Apr 2018

Feature selection is a significant aspect of speech emotion recognition system. How to select a small subset out of the thousands of speech data is important for accurate classification of speech emotion.

The main aim of the project is to decrease computation time of Emotion Detection Mechanism by using less possible features while retaining significant accuracy.

Experiments are conducted on the EMODB and IITKGP-SEHSC databases, demonstrating that size of each subset reduced to 50% of the size of original feature set, however, the accuracy remained almost same as original ones

(Tool used: MATLAB)

Speech Emotion Recognition using Dynamic Time Warping

Jan 2017 - Apr 2017

The purpose of speech emotion recognition system is to automatically classify speaker's utterances into five emotional states such as disgust, boredom, sadness, neutral, and happiness.

In this project, we extracted MFCC features from each frame and developed a trained model for detecting emotion using DTW classifier and obtained accuracy of 68.57%

(Tool used: MATLAB)

Electronic Piano

July 2016 - Oct 2016

Built a piano with variable tuning feature using IC 555 in Astable mode.

IC sends high/low frequency signals to a piezo buzzer based on the value of resistance corresponding to the key/button

Introduced potentiometers to obtain custom octave frequencies.

(Tools used: Eagle, Circuit Maker, IC 555, Resistors, Capacitors, Speaker and Potentiometers)

COMPETITION PROJECTS

Line Follower Robot

Sept 2015

Built a line follower robot for a National Robotic Championship Organized by ARK tech in association with IIT Madras held at IIT Bombay.

The Line follower robot is a mobile machine that can detect and follow the line drawn on the floor.

Programmed Arduino to control motors of robot according to map.

Collector Bot

Nov 2017 - Mar 2018

This bot is built for Eyantra online robotics competition and my theme was in agriculture domain.

Our team reached till a final task of competition.

The arena for the theme is an abstraction of a farm with fallen fruits in it. An autonomous robot build from scratch collects the Fresh fruit and avoids the damaged fruit.

Feedback from the overhead camera is processed to direct the robot. Position and nature of the fruits are determined by ArUco markers.

The whole arena was redesigned in V-REP simulator and path planning module was scripted in LUA in V-REP, over which the actual bot had to move over the arena.

So simulation of the real life scenario was done inside V-REP and the necessary data to control the motion of bot was sent to it via X-Bee module which works on UART.

Also, the motion of bot was controlled using PID algorithm to make sure bot follows the path created in V-REP simulator. Further, the robot also has to transfer the fruits into another independent robot which is moving in the farm in a path.

TECHNICAL SKILLS

- **Programming languages:** C, MATLAB , Java, Python, Lua
- **Software Packages:** MATLAB , Octave, Eagle, Circuit Maker, V-REP
- **Miscellaneous:** Arduino programming, Video Editing

SUMMER TRAINING DETAILS

- **Certificate Course in IP Networking** at *CETTM, Powai* **July 2017**
- **Short Term Training Program** on “Basic Electrical Testing” at *Syselec Technologies Pvt. Ltd* **July 2016**

ACHIEVEMENTS AND EXTRA CURRICULAR ACTIVITIES

- Qualified **GATE** in 2018
- **Eyantra online robotics competition:** Reached till a final task of competition.
- **National Robotic Championship Organized by ARK tech in association with IIT Madras:** Zonal winner of Mumbai and Represented SFIT in Finale at IIT Bombay
- **PRAYAS 2015:** Presented Laser Security System along with Colour Recognition Lock.
- **MOSAIC:** Leader of Mosaic (2016) Contraption Team
- Participated in “**3rd National level Technical Paper Presentation**” organized by Universal College of Engineering